

Controllability of the heat equation submitted to unilateral constraint

Farid Ammar-Khodja ^{*} Arnaud Münch [†]

July 7, 2016

Abstract

Mathematics Subject Classification. 35L85, 65M12, 74H45

Keys words. Nonlinear boundary controllability, Unilateral constraint, Penalization, Fixed point method.

1 Introduction

Let $T > 0$ and $Q_T = (0, T) \times (0, 1)$. We consider the following system

$$\begin{cases} y' - y_{xx} = 0, & (t, x) \in Q_T, \\ y(t, 0) = u(t), & t \in (0, T), \\ y(t, 1) \geq \psi(t), y_x(t, 1) \geq 0, (y(t, 1) - \psi(t))y_x(t, 1) = 0, & t \in (0, T), \\ y(0, x) = y^0(x), & x \in (0, 1) \end{cases} \quad (1.1)$$

where the symbol $'$ denotes the derivative with respect to the variable t .

2 The Control Dirichlet-to-Neumann map of a linear system

Let $T > 0$, $Q_T = (0, T) \times (0, 1)$ and consider the following system:

$$\begin{cases} \epsilon\phi'' + \phi' - \phi_{xx} = 0, & (t, x) \in Q_T, \\ \phi(t, 0) = u(t), & t \in (0, T), \\ \phi(t, 1) = f(t), & t \in (0, T), \\ \phi(0, x) = \phi^0(x), \quad \phi'(0, x) = \phi^1(x), & x \in (0, 1) \end{cases} \quad (2.2)$$

where $u \in L^2(0, T)$ is a control function and $f \in L^2(0, T)$ is given.

Given (ϕ^0, ϕ^1, f) , our aim is to find a family of explicit controls u for which the solution ϕ of (2.2) satisfies $\phi(T) = \phi'(T) = 0$ in $(0, 1)$. We take $T \in]2, 3]\sqrt{\epsilon}$.

^{*}Laboratoire de Mathématiques de Besançon, UMR CNRS 6623, Université de Franche-Comté, 16 route de Gray, 25030 Besançon cedex, France (farid.ammar-khodja@univ-fcomte.fr).

[†]Laboratoire de Mathématiques de Clermont-Ferrand, Université Blaise Pascal, UMR CNRS 6620, Campus des Cézeaux, 63177 Aubière, France - arnaud.munch@math.univ-bpclermont.fr.

Setting

$$p = \phi' - \frac{1}{\sqrt{\epsilon}}\phi_x, \quad q = \phi' + \frac{1}{\sqrt{\epsilon}}\phi_x, \quad (2.3)$$

it follows that (2.2) is equivalent to

$$\begin{cases} p' + \frac{1}{\sqrt{\epsilon}}p_x + \frac{1}{2\epsilon}(p+q) = 0, & (t, x) \in Q_T, \\ q' - \frac{1}{\sqrt{\epsilon}}q_x + \frac{1}{2\epsilon}(p+q) = 0, & (t, x) \in Q_T, \\ (p+q)(\cdot, 0) = 2u', & t \in (0, T), \\ (p+q)(\cdot, 1) = 2f' & t \in (0, T), \\ p^0 = \phi^1 - \frac{1}{\sqrt{\epsilon}}\phi_x^0, q^0 = \phi^1 + \frac{1}{\sqrt{\epsilon}}\phi_x^0, & x \in (0, 1). \end{cases} \quad (2.4)$$

We introduce $P = (p, q)$ the solution of

$$P' = \frac{1}{\sqrt{\epsilon}}MP_x - \frac{1}{2\epsilon}AP \quad (2.5)$$

with

$$M = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}, \quad A = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \quad (2.6)$$

leading to

$$P(t, x(t)) = e^{-\frac{t}{2\epsilon}A}P(t_0, x(t_0)), \quad \forall t \geq t_0$$

where the characteristic $x(t)$ satisfies

$$x'(t) = \pm \frac{1}{\sqrt{\epsilon}}$$

Remark 2.1

$$e^{-\frac{t}{2\epsilon}A} = \frac{1}{2} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix} + \frac{1}{2}e^{-\frac{t}{\epsilon}A} \quad (2.7)$$

2.1 $p(x, T)$ in term of p^0 and q^0

Let

$$\bar{x} = \frac{T - 2\sqrt{\epsilon}}{\sqrt{\epsilon}} \in (0, 1)$$

Let $x_0 \in (\bar{x}, 1)$ (two reflections at $x = 0$ then $x = 1$ before to reach $t = 0$). We got

$$\begin{cases} p(x_0, T) = a(T)p(0, t_1) + b(T)q(0, t_1), \\ p(0, t_1) = 2u'(t_1) - q(0, t_1), \\ q(0, t_1) = b(t_1)p(1, t_2) + c(t_1)q(1, t_2), \\ q(1, t_2) = 2f'(t_2) - p(1, t_2), \\ p(1, t_2) = a(t_2)p(x_3, 0) + b(t_2)q(x_3, 0) = a(t_2)p^0(x_3) + b(t_2)q^0(x_3) \end{cases}$$

leading to

$$\begin{aligned} p(x_0, T) &= 2a(T)u'(t_1) \\ &\quad + 2c(t_1)[b(T) - a(T)]f'(t_2) \\ &\quad + [b(T) - a(T)][b(t_1) - c(t_1)][a(t_2)p^0(x_3) + b(t_2)q^0(x_3)] \end{aligned} \quad (2.8)$$

with

$$\begin{aligned} t_1 &= T - \sqrt{\epsilon}x_0 \in (T - \sqrt{\epsilon}, 2\sqrt{\epsilon}) \\ t_2 &= t_1 - \sqrt{\epsilon} = T - \sqrt{\epsilon}(x_0 + 1) \in (T - 2\sqrt{\epsilon}, \sqrt{\epsilon}), \\ x_3 &= \frac{\sqrt{\epsilon} - t_2}{\sqrt{\epsilon}} \in (0, \frac{3\sqrt{\epsilon} - T}{\sqrt{\epsilon}}) \end{aligned} \quad (2.9)$$

and

$$\begin{pmatrix} a(t) & b(t) \\ b(t) & c(t) \end{pmatrix} := e^{-\frac{t}{2\epsilon}A}. \quad (2.10)$$

Writing that $p(x_0, T) = 0$, we get that, for all $t_1 \in (T - \sqrt{\epsilon}, 2\sqrt{\epsilon})$, a first relation between u' and f' :

$$\begin{aligned} 0 &= 2a(T)u'(t_1) \\ &+ 2c(t_1)[b(T) - a(T)]f'(t_1 - \sqrt{\epsilon}) \\ &+ [b(T) - a(T)][b(t_1) - c(t_1)] \left(a(t_1 - \sqrt{\epsilon})p^0\left(\frac{2\sqrt{\epsilon} - t_1}{\sqrt{\epsilon}}\right) + b(t_1 - \sqrt{\epsilon})q^0\left(\frac{2\sqrt{\epsilon} - t_1}{\sqrt{\epsilon}}\right) \right) \end{aligned} \quad (2.11)$$

Let now $x_0 \in (1, \bar{x})$ (three reflections at $x = 0$ then $x = 1$ then $x = 0$ before to reach $t = 0$). We got

References

- [1] P. Bénilan and M. Pierre, *Inéquation différentielles ordinaires avec obstacles irréguliers*. Ann. Fac. Sc. Toulouse. 5^e série, tome 1, **1** (1979), 1-8.
- [2] J.-M. Coron, *Control and nonlinearity*. Mathematical Surveys and Monographs, 136. American Mathematical Society, Providence, RI, 2007.
- [3] Y. Dumont and L. Paoli, *Vibrations of a beam between obstacles. Convergence of a fully discretized approximation*, Mathematical Modelling and Numerical Analysis, **40** (2006), 705-734.
- [4] N. Kikuchi and J.T. Oden, *Contact problems in elasticity: a study of variational inequalities and finite element methods.*, SIAM Studies in Applied Mathematics, **8**. Philadelphia, PA, 1988.
- [5] J.U. Kim, *A boundary thin obstacle problem for a wave equation*, Commun. in Partial Differential Equation, **14** (1989), 1011-1026.
- [6] G. Lebeau and M. Schatzman, *A wave problem in a half space with a unilateral constraint at the boundary*, J. Differential Equations, **53** (1984), 309-361.
- [7] J.-L. Lions, *Contrôlabilité exacte, perturbations et stabilisation de systèmes distribués*, Vol. 8 RMA Masson Paris, 1988.
- [8] J.-L. Lions and E. Magenes, *Problèmes aux Limites non Homogènes et Applications*, Vol. 1-2, Dunod, 1968.
- [9] J.E. Rivera and H.P. Oquendo, *Exponential decay for a contact problem with local damping*, Funkcialaj Ekvacioj, **42** (1999), 371-387.

- [10] D. L. Russell, *Controllability and stabilizability theory for linear partial differential equations: recent progress and open questions*, SIAM Review, **20** (1978), 639-739.
- [11] M. Schatzman, *An hyperbolic problem of second order with unilateral constraints: the vibrating string with a concave obstacle*, J. Mathematical Analysis and Applications, **73** (1980), 138-191.
- [12] M. Schatzman, *Un problème hyperbolique du 2ème ordre avec contrainte unilatérale: la corde vibrante avec obstacle ponctuel*, J. Differential Equations, **36** (1980), 295-334.
- [13] M. Schatzman and M. Bercovier, *Numerical approximation of a wave equation with unilateral constraints*, Mathematics of Computations, **53** (1989), 55-79.
- [14] E. Zuazua, *Exact controllability for the semilinear wave equation*, J. Math. Pures et Appl., **69** (1990), 1-31.