# Loci selection in model-based clustering

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### Introduction

- We wish to discover the unknown genetic structure of a target diploid population from a *n*-sample without prior information.
- It may happen that some loci are just noise or event harmful for clustering purposes.

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- We wish to discover the unknown genetic structure of a target diploid population from a *n*-sample without prior information.
- It may happen that some loci are just noise or event harmful for clustering purposes.
- Which loci cluster the sample in the "best" way?
- We propose to simultaneously solve the loci selection and clustering problem by a model selection procedure for density estimation.
- An associated stand alone C++ package named MixMoGenD is available free of charge on www.math.u-psud.fr/~toussile.

# Outline

### Methods

- Competing models
- Model selection via penalization

### 2 Consistency

### 3 Selection procedure

- Selection procedure in practice
- Numerical experiments using BIC

Framework

- Consider a random vector  $X = (X')_{I=1,...,L}$  with  $L \ge 2$ .
- With  $X^{l} = \{X^{l,1}, X^{l,2}\}$ , where  $X^{l,1}, X^{l,2}$  are nominal variables taking values in the set  $\{1, \ldots, A_{l}\}$  of allele states at locus *l*.

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- Assume that the clusters are characterized by:

(LE) Conditional complete independence of the random variables X'; (HWE) Conditional independence of  $X^{l,1}$  and  $X^{l,2}$  at any locus X'. [Pritchard et al., 2000, Chen et al., 2006, Corander et al., 2008].



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  (LE) Conditional complete independence of the random variables X<sup>1</sup>;
  (HWE) Conditional independence of X<sup>1,1</sup> and X<sup>1,2</sup> at any locus X<sup>1</sup>.
  [Pritchard et al., 2000, Chen et al., 2006, Corander et al., 2008].
  - Now, assume that only some loci gathered in a subset S are relevant for clustering purposes.
  - Also assume that for any  $l \notin S$ ,  $X^{l}$  is identically distributed across all clusters.

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### Modeling Competing models

•  $\Rightarrow$  In model-based settings,  $X \sim P_0$  of the form

$$P_{(K,S,\theta)}(x) = \left[\sum_{k=1}^{K} \pi_{k} \prod_{l \in S} (2 - \mathbb{1}_{x^{l,1} = x^{l,2}}) \alpha_{k,l,x^{l,1}} \times \alpha_{k,l,x^{l,2}}\right] \times \prod_{l \notin S} (2 - \mathbb{1}_{x^{l,1} = x^{l,2}}) \beta_{l,x^{l,1}} \beta_{l,x^{l,2}}$$
(1)

where  $\theta = (\pi, \alpha, \beta) \in \Theta_{(K,S)} = \cdots$ .

- Model  $\mathcal{M}_{(K,S)} := \{ P_{(K,S,\theta)} | \ \theta \in \Theta_{(K,S)} \}.$
- Inferring  $(K, S) \iff$  model selection among  $C = \{\mathcal{M}_{(K,S)} | (K, S) \in \mathbb{M}\}$  for the estimation of  $P_0$ , where  $\mathbb{M}$ is the set of all possible (K, S).

Model selection via penalization ([Massart, 2007])

Selected model

$$(\widehat{K}_n, \ \widehat{S}_n) = \arg\min_{(K, S)} \operatorname{crit}(K, S).$$
 (2)

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• Where crit is a penalyzed maximum likelihood criterion

$$\operatorname{crit}(K, S) = \underbrace{\gamma_n\left(\widehat{P}_{(K,S)}\right)}_{\mathbb{P}_n\left(-\ln\widehat{P}_{(K,S)}\right):=\frac{1}{n}\sum_{i=1}^n -\ln P_{(K,S,\widehat{\theta}_{MLE})}(X_i)} + \operatorname{pen}(K, S);$$
(3)

• Selected estimator  $P_{(\widehat{K}_n, \widehat{S}_n, \widehat{\theta}_{MLE})}$  and classification by MAP.

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Selected estimator P<sub>(Kn,Sn,BMLE)</sub> and classification by MAP.
 The most used asymptotic penalized likelihood criteria:

$$\mathbf{BIC}(K,S) = \mathbb{P}_n\left(-\ln\widehat{P}_{(K,S)}\right) + \frac{\ln n}{2n}D_{(K,S)}$$
$$\mathbf{AIC}(K,S) = \mathbb{P}_n\left(-\ln\widehat{P}_{(K,S)}\right) + \frac{1}{n}D_{(K,S)}.$$

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- Although there exists a lot of articles concerning the behavior of the BIC and other penalization methods in practice, theoretical results in a mixture framework are few: the consistency of the BIC estimator is shown
  - ▶ in [Maugis et al., 2009] for a variable selection problem,
  - ► and in [Keribin, 2000] for the number of components, in Gaussian mixture models framework.
- But as far as we know, there is no consistency result for both a variable selection and clustering problem in a discrete distribution setting.

• Consider a penalty function  $\mathbf{pen} = \mathbf{pen}(D, n)$  such that:

- (P1): for any positive integer D,  $\lim_{n\to\infty} \mathbf{pen}(D, n) = 0$ ;
- (P2): for any  $\mathcal{M}_1 \subsetneq \mathcal{M}_2$ , one has

$$\lim_{n\to\infty}\left[n\left(\operatorname{pen}\left(D_{2}, n\right) - \operatorname{pen}\left(D_{1}, n\right)\right)\right] = \infty$$

• Let  $(\widehat{K}_n, \widehat{S}_n)$  be a minimizer of **crit** over a sub-collection  $\mathcal{C}_{K_{\max}}$  for a given maximum number  $K_{\max}$  of clusters.

### Theorem ([Toussile and Gassiat, 2009])

If  $P_0 > 0$  and belongs to one of the competing models in  $C_{K_{max}}$ , then there exists an identifiable "smallest" model  $(K_0, S_0)$  such that

$$\lim_{n\to\infty} P_0\left[\left(\widehat{K}_n, \ \widehat{S}_n\right) = (K_0, \ S_0)\right] = 1.$$
 (5)

• Example: BIC.

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Definition of  $\mathcal{M}_{(K_0,S_0)}$ 

#### Lemma

For every  $K_1$  and  $K_2$  in  $\mathbb{N}^*$ , and  $S_1$  and  $S_2$  in  $\mathcal{P}^*(L)$ ,  $\mathcal{M}_{(K_1,S_1)} \cap \mathcal{M}_{(K_2,S_2)} = \mathcal{M}_{(\min(K_1,K_2),S_1 \cap S_2)}$ .

The "smallest" model is defined by  $(K_0, S_0) := (K(P_0), S(P_0))$ , where

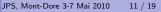
$$K(P) = \min \left\{ K \mid P \in \bigcup_{S \in \mathcal{P}^*(L)} \mathcal{M}_{(K, S)} \right\},$$
(6)  
$$S(P) = \min \left\{ S \mid P \in \bigcup_{K \in \mathbb{N}^*} \mathcal{M}_{(K, S)} \right\},$$
(7)

for every P in one of the competing models  $\mathcal{M}_{(K, S)} \in \mathcal{C}_{\mathcal{K}_{max}}$ .



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It suffices to show that 
$$\lim_{n\to\infty} P_0\left[\gamma_n\left(\widehat{P}_{(K_0, S_0)}\right) - \gamma_n\left(\widehat{P}_{(K, S)}\right)\right] >$$
  
**pen** $(K, S)$  - **pen** $(K_0, S_0)$  = 0 for any  $(K, S) \neq (K_0, S_0)$ .



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$$P_0 \notin \mathcal{M}_{(K,S)}:$$



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$$P_{0} \in \mathcal{M}_{(K,S)}:$$
  
- $n\gamma_{n}(P_{0}) \leq -n\gamma_{n}\left(\widehat{P}_{(K_{0}, S_{0})}\right) \leq -n\gamma_{n}\left(\widehat{P}_{(K, S)}\right) \leq \sup_{P \in \mathcal{D}}\left(-n\gamma_{n}(P)\right).$ 

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:  
 $-n\gamma_n(P_0) \leq -n\gamma_n\left(\widehat{P}_{(K_0, S_0)}\right) \leq -n\gamma_n\left(\widehat{P}_{(K, S)}\right) \leq \sup_{P \in \mathcal{D}} (-n\gamma_n(P)).$ 

$$P_{0} \notin \mathcal{M}_{(K,S)}:$$
  

$$\gamma_{n} \left( \widehat{P}_{(K_{0}, S_{0})} \right) - \gamma_{n} \left( \widehat{P}_{(K, S)} \right) =$$
  

$$- \inf_{\theta \in \Theta_{(K, S)}^{\delta}} E_{P_{0}} \left[ \ln P_{0} \left( X \right) - \ln P_{(K, S)} \left( X \mid \theta \right) \right] + o_{P_{0}} \left( 1 \right),$$
  
where  $\Theta_{(K,S)}^{\delta} = \left\{ \theta \in \Theta_{(K,S)}: P_{(K,S,\theta)} \ge \delta \right\}$ 

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Theorem ([Toussile and Gassiat, 2009])

If  $P_0 > 0$ , there exists a real  $\delta > 0$  such that for every (K, S), one has

$$-\gamma_{n}\left(\widehat{P}_{(K,S)}\right) = \sup_{\theta \in \Theta_{(K,S)}^{\delta}} \left\{-\gamma_{n}\left(P_{(K,S,\theta)}\right)\right\} + o_{P_{0}}\left(1\right) \quad (8)$$

and

$$\sup_{\theta \in \Theta_{(K,S)}} E_{P_0} \left[ \ln P_{(K,S,\theta)}(X) \right] = \sup_{\theta \in \Theta_{(K,S)}^{\delta}} E_{P_0} \left[ \ln P_{(K,S,\theta)}(X) \right].$$
(9)

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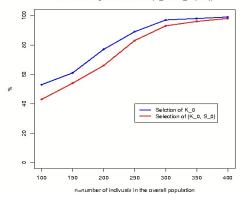
### Selection procedure in practice

- An exhaustive search of the optimum model is very painfull in most situations.
- A two nested algorithm based on Backward-Stepwise proposed in [Maugis et al., 2009] could miss the optimum model in some cases, in particular in cases where the optimum subset of clustering loci is small.
- In MixMoGenD, we prefer a modified Backward-Stepwise algorithm with which sets *S* with small cardinality are always explored for any value of *K* [Toussile and Gassiat, 2009].
- The optimum model is then chosen between all the explored models.

BACKWARD-STEPWISE EXPLORER(crit, K)  $S \leftarrow \{1, \ldots, L\}, c_{ex} \leftarrow 0, c_{in} \leftarrow 0$ 1 2 repeat 3 EXCLUSION(K, S) {  $c_{ex} \leftarrow \arg\min_{l \in S} \operatorname{crit}(K, S \setminus \{l\})$ 4 if crit (K, S) – crit  $(K, S \setminus \{c_{ex}\}) \ge 0$  or  $c_{in} = 0$ 5 6 then  $S \leftarrow S \setminus \{c_{ex}\}$ 7 8 INCLUSION(K, S) { 9  $c_{in} \leftarrow \arg\min_{l \notin S} \operatorname{crit}(K, S \cup \{l\})$  $\text{if} \left( \operatorname{crit} \left( K, \ S \cup \{ c_{in} \} \right) - \operatorname{crit} \left( K, \ S \right) < 0 \text{ and } S \cup \{ c_{in} \} \text{ have} \right)$ 10 never been the current set in an EXCLUSION step 11 12 then  $S \leftarrow S \cup \{c_{in}\}$ 13 else  $c_{in} \leftarrow 0$ 14 15 **until** |S| = 1.

# Numerical experiments using BIC Consistency

Figure: Percentage of selecting the true model using the BIC



% of selecting the true model (K\_0=2, S\_0={1, 2})

## Numerical experiments using BIC

- L = 10,  $A_I = 10$ ,  $K_0 = 5$ ,  $|S_0| \in \{2, 4, 6, 8\}$ .
- 30 datasets with n = 1000 for each value of  $|S_0|$ .
- $F_{ST} \in [0.0181, 0.0450]$  a range where clustering is thought to be difficult.

Table: Thresholds of  $F_{ST}$  for which MixMoGenD perfectly selects the true model.  $F_{ST}^{S}$ : with loci selection;  $F_{ST}$ : without loci selection.

$ S_0 $	8	6	4	2
$F_{ST}^S$	0.0342	0.0307	0.0316	0.0248
$F_{ST} >$	0.0425	0.0410	0.0413	0.0350

• The improvement on the estimation of K and the prediction capacity is obviously due to the variable selection procedure.

# Numerical experiments using BIC

Data	F <sub>ST</sub>	<i>R</i> <sub>n</sub>	% WA	$\widehat{K}_n^s$	% WA <sup>s</sup>	Data	F <sub>ST</sub>	<i>R</i> <sub>n</sub>	% WA	$\widehat{K}_n^s$	% WA <sup>s</sup>
1	0.0306	3	-	3	-	16	0.0381	5	10.90	5	10.30
2	0.0318	3	-	3	-	17	0.0382	5	09.30	5	08.80
3	0.0328	3	-	3	-	18	0.0390	4	-	5	09.10
4	0.0331	3	-	3	-	19	0.0400	5	08.80	5	08.00
5	0.0335	3	-	4	-	20	0.0404	4	-	5	09.50
6	0.0337	3	-	3	-	21	0.0425	5	06.30	5	05.40
7	0.0340	4	-	4	-	22	0.0427	5	07.10	5	07.50
8	0.0342	3	-	5	11.80	23	0.0427	5	05.90	5	05.90
9	0.0348	3	-	5	12.40	24	0.0435	5	06.70	5	06.50
10	0.0362	3	-	5	09.10	25	0.0436	5	07.10	5	06.60
11	0.0373	4	-	5	08.90	26	0.0440	5	05.50	5	05.70
12	0.0373	5	08.50	5	07.60	27	0.0442	5	07.20	5	06.80
13	0.0377	5	11.40	5	10.40	28	0.0449	5	07.20	5	06.70
14	0.0377	5	10.50	5	10.20	29	0.0449	5	06.10	5	06.30
15	0.0377	5	10.30	5	10.20	30	0.0450	5	06.10	5	05.60

Table: 30 samples each with n = 1 000,  $K_0 = 5$ , L = 10,  $|S_0| = 8$  and  $F_{ST} \in [0.0306, 0.0450]$ . % WA and % WA<sup>s</sup> = percentage of wrongly assigned individuals without and with loci selection respectively;  $\hat{K}_n$  and  $\hat{K}_n^s$  = the estimates of the number of populations without and with loci selection respectively.  $\hat{S}_n = S_0$ .



# Conclusion and perspectives

- Theoretical result on the consistency of the **BIC** type criteria is also valid for the variable selection problem in clustering with multinomial mixture models.
- As expected, the variable selection procedure significantly improves the inference on the number of clusters and the prediction capacity.

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- Theoretical result on the consistency of the **BIC** type criteria is also valid for the variable selection problem in clustering with multinomial mixture models.
- As expected, the variable selection procedure significantly improves the inference on the number of clusters and the prediction capacity.
- Robustness of the selection procedure with respect to HWE and LE assumptions.
- Is it the same set S of loci that discriminates all populations?
- **BIC**, as well as **AIC**, relies on a strong asymptotic assumption, and can thus be inappropriate for small sample sizes.



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